Based on Form PTO-1449 (3/90)	ATTY. DOCKET NO. 450100-02856.2	SERIAL NO. 10/775,845 Filed Concurrently Herewith
LIST OF REFERENCES CITED BY APPLICANT (Use several sheets if necessary)	APPLICANT Yuichi HATTORI et al.	
	FILING DATE Filed Concurrently Herewith	GROUP 3661

U.S. PATENT DOCUMENTS

EXAMINER INITIAL		DOCUMENT NUMBER	DATE	NAME	CLASS	SUBCLASS	FILING DATE IF APPROPRIATE
m.m	AA	5,404,086	4/95	Takenaka et al.	318	568.11	
	AB	5,737,217	4/98	Nishikawa et al.	180	8.6	
	AC	6,362,589	3/02	Inoue et al.	318	568.1	
	AD	US2001-0049248	2/01	Choi,Kei Fung	446	356	
	AE	5,928,093	7/99	Lai	473	430	
	AF	5,928,389	11/99	Guenter et al.	345	474	
	AG	6,266,576 B1	7/01	Okada et al.	700	245	
	AH	5,357,433	10/1994	Takenaka et al.	701	23	
	AI	6,064,167	05/2000	Halfmann, Jurgen	318	439	
	AJ	6,289,265	09/2001	Takenaka et al.	700	245	
	AK	6,463,356	10/2002	Hattori et al.	700	245	

FOREIGN PATENT DOCUMENTS

		DOCUMENT NUMBER	DATE	COUNTRY	CLASS	SUBCLASS	TRANSLATION YES	TRANSLATION NO
m.m	AL	6-31658	2/8/94	Japan				
	AM	7-205085	8/8/95	Japan				
	AN	9-142347	6/3/97	Japan				
	AO	PCT/JP99/03089		WIPO				
	AP	0 661 614 A2	7/95	EPO				
	AQ	1 103 450 A1	5/01	EPO				
	AR	JP 237979 A	2/99	Japan				
	AS	1 103 451 A2	5/01	EPO				
	AT	407222833A	8/95	Japan				

Based on Form PTO-1449 (3/90)	ATTY. DOCKET NO. 450100-02856.1	SERIAL NO. 10/775,845 Filed ~~Concurrently Herewith~~
LIST OF REFERENCES CITED BY APPLICANT (Use several sheets if necessary)	APPLICANT Yuichi HATTORI et al.	
	FILING DATE Filed Concurrently Herewith	GROUP 3661

			OTHER PRIOR ART (Including Author, Title, Date, Pertinent Pages, Etc.)
m.m	AU		~~Microfilm of the specification and drawings annexed to the request of Japanese Utility Model~~ Application No. 63-85017 (Laid-open No. 2-8498)
	AV		INABA M ET AL: "TWO-ARMED BIPEDAL ROBOT THAT CAN WALK, ROLL OVER AND STAND UP" PROCEEDINGS. 1995 IEEE/RSJ INTERNATIONAL CONFERENCE ON INTELLIGENT ROBOTS AND SYSTEMS. HUMAN ROBOT INTERACTION AND COOPERATIVE ROBOTS (CAT. NO. 95CB35836), PROCEEDINGS 1995 IEEE/RSJ INTERNATIONAL CONFERENCE ON INTELLIGENT ROBOTS AND SYSTEMS. HUMAN ROB, PAGES 297-302, VOL. 3, XP002164248 1995, LOS ALAMITOS, CA, USA, IEEE COMPUT. SOC. PRESS, USA
	AW		INABA M ET AL: "A 35 DOF HUMANOID THAT CAN COORDINATE ARMS AND LEGS IN STANDING UP, REACHING AND GRASPING AN OBJECT" PROCEEDINGS OF THE IEEE/RSJ INTERNATIONAL CONFERENCE ON ROBOTS AND SYSTEMS, US, NEW YORK, IEEE, 4 November 1996, pages 29-36, XP000773256
	AX		HUGEL V ET AL: "REACTIVE AND ADAPTIVE CONTROL ARCHITECTURE DESIGNED FOR THE SONY LEGGED ROBOTS LEAGUE IN ROBOCUP 1999" PROCEEDINGS. 2000 IEEE/RSJ INTERNATIONAL CONFERENCE ON INTELLIGENT ROBOTS AND SYSTEMS (IROS 2000) (CAT. NO. 00CH37113), PROCEEDINGS. 2000 IEEE/RSJ INTERNATIONAL CONFERENCE INTELLIGENT ROBOTS AND SYSTEMS (IROS 2000), TAKAMATSU, JAPAN, 31 Oct.-5 Nov., pages 1032-1037, vol. 2, XP002164249
	AY		Thomas Braunl, Robot soccer by autonomous intelligent vehicles, November 2000, Internet pp1-2
	AZ		Thomas Braunl, EyeBot, November 2000, Internet pp 1-2
	BA		Jung et al., Fuzzy rule extraction for shooting action controller of soccer robot, 1999, IEEE, pp. 1-556-1-561
	BB		Astley et al., Design constraints for haptic surgery simulation, 2000, IEEE, pp. 2446-2451
	BC		Rosen et al., Markov modeling of minimally invasive surgery based on tool/tissue interaction and force/torque signatures for evaluating surgical skill, 2001, IEEE, pp. 579-591
	BD		PATENT ABSTRACTS OF JAPAN, 2000-061872, PUBLICATION DATE, 29 FEBRUARY 2000
	BE		PATENT ABSTRACTS OF JAPAN, 63-191528, PUBLICATION DATE, 9 AUGUST 1988
	BF		PATENT ABSTRACTS OF JAPAN, 61-054378, PUBLICATION DATE, 18 MARCH 1986
	BG		PATENT ABSTRACTS OF JAPAN, 07-205070, PUBLICATION DATE, 8 AUGUST 1995

EXAMINER	DATE CONSIDERED
McDieunel Marc	4-18-05

* EXAMINER: Initial if reference considered, whether or not citation is in conformance with MPEP 609. Draw line through citation if not in conformance and not considered. Include copy of this form with next communication to applicant.